TENTATIVE

TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

T A 8 8 5 9 C P

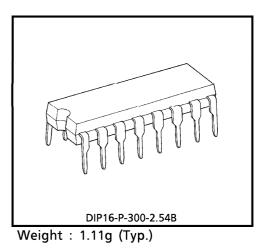
TV BIAS DISTORTION COMPENSATION IC

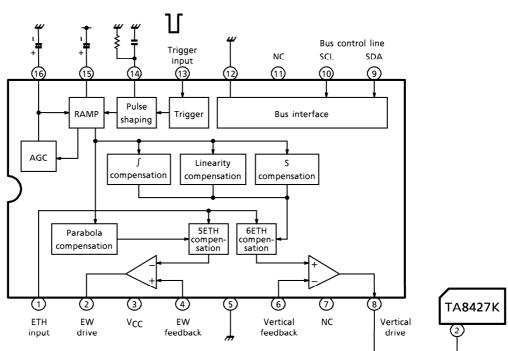
The TA8859CP is an IC for TV deflection stage to compensate various horizontal, vertical distortion, with a package of 16 pin DIP, controlled via I²C bus.

FEATURES

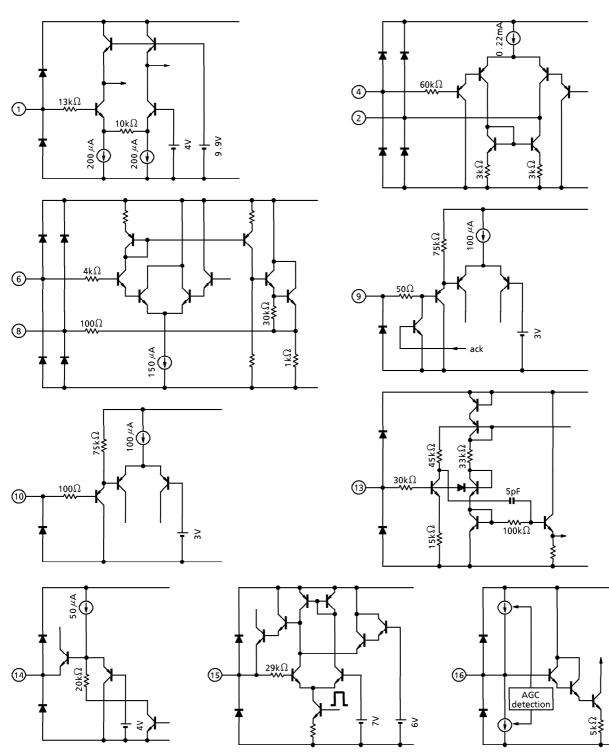
- Vertical linearity correction
- Vertical S correction
- E-W parabola
- E-W corner
- Trapezium distortion compensation

BLOCK DIAGRAM





TERMINAL INTERFACE



OUTLINE OF FUNCTIONS

FUNCTION	SUB ADDRESS	BIT	OUTPUT WAVEFORM	PICTURE
Picture Height Adjustment	0010	6		
Vertical Linearity correction	0011	5		Lower expansion upper contraction
Vertical "S " Correction (X ³)	0100	5	11	
Vertical Shift	0101	3		Upper and lower contraction
Vertical Compensation	0110			Correction of distortion caused by high-voltage fluctuations
Picture Width Adjustment	0111	6		
E-W Parabola	1000	6	Ϋ́Ϋ́Ϋ́	

FUNCTION	SUB ADDRESS	BIT	OUTPUT WAVEFORM	PICTURE
E-W Corner Correction	1001	4		Corner maximum
Trapezium Distortion Compensation	1010	6	VII	
Horizontal Compensation	1011	_	$\sqrt{2}$	Correction of distortion caused by high-voltage fluctuations
Vertical ∫ Correction (X ⁵)	1110	4	11	Upper and lower contraction

I²C BUS CONTROL FUNCTIONS

FUNCTION	SUB ADDRESS	DATA	PRESET	RANGE
Picture Height	00000010	×-×-7bit	01000000	- 48~48%
V-linearity	00000011	×-×-×-5bit	00010000	- 13~ 13%
V-S Correction	00000100	×-×-×-5bit	0000000	0~22%
V-shift	00000101	x-x-x-AGC-3bit-x	00001000	-800~800mV
V-compensation	00000110	$\times - \times - \times - \times - 4$ bit	0000000	0~9%
Picture Width	00000111	×-×-6bit	00100000	1.6~7.3V
E-W Parabola	00001000	×-×-6bit	00100000	0~5.6V
E-W Corner	00001001	$\times - \times - \times - \times - 4$ bit	0000000	0~3.2V
Trapezium	00001010	×-×-6bit	00100000	0~1.2V
H-compensation	00001011	x-x-x-4bit	00000000	0~9%
V-∫ Correction	00001100	x-x-x-4bit	0000000	0~4%

(Note 1) Vertical Height is controlled by Sub Address 02 (H), so no external control is required.

- (Note 2) AGC bit determines vertical AGC response speed.
 0 : High speed for Channel/Mode change
 1 : Low speed (1/5 x High speed) for Normal recention
 - 1 : Low speed (1/5×High speed). for Normal reception/Text Mode.
- (Note 3) All registers are cleared into the preset value under the condition of $V_{CC} \leq 3V$.

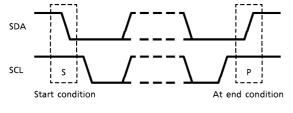
I²C BUS CONTROL FORMAT OUTLINE

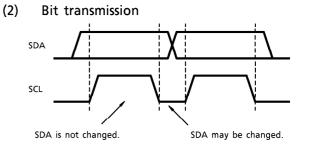
Bus controlled format of TA8859CP is based on I²C Bus Control format of PHILIPS.

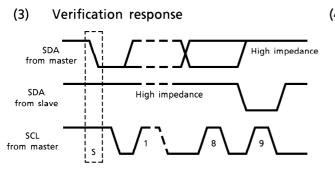
Data transmission format



(1) Start condition, at end condition







(4) Slave address

A6	A5	A4	A3	A2	A1	A0	R/W
1	0	0	0	1	1	0	0

Purchase of TOSHIBA I²C components conveys a license under the Philips I²C Patent Rights to use these components in an I²C system, provided that the system conforms to the I²C Standard Specification as defined by Philips.

MAXIMUM RATINGS (Ta = 25° C, V_{CC} = 12V)

CHARACTERISTIC	SYMBOL	RATING	UNIT
Supply Voltage	Vcc	15	V
Power Dissipation	PD max	1.4 (Note)	W
Input Signal Voltage	e _{in}	5	V _{p-p}
Operating Temperature	T _{opr}	- 20~65	°C
Storage Temperature	T _{stg}	- 55~150	°C

(Note) Derated above $Ta = 25^{\circ}C$, in the proportion of $11.2mW/^{\circ}C$.

RECOMMENDED POWER SUPPLY VOLTAGE

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply Voltage	V _{CC}	10.8	12	13.2	V

ELECTRICAL CHARACTERISTICS

(Unless otherwise specified, $V_{CC} = 12V$, Ta = 25°C) Power supply current

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply Current	lcc	20	30	45	mA

Terminal voltage

No.	ITEM	SYMBOL	MIN.	TYP.	MAX.	UNIT	ΝΟΤΕ
1	⊿EHT	V ₁	7.5	8.0	8.5		—
2	EW-OUT	V ₂	5.8	6.1	6.4		—
3	V _{CC} (12V)	V ₃	—	12.0	—		Terminal = V_{CC} (12.0V)
4	EW-FB	V4	—	12.0	_		Terminal = V_{CC} (12.0V)
5	GND	V5		0.0			Terminal = GND
6	V.FB	V ₆	2.0	2.4	2.8		—
7	N.C.	V ₇		0.0			Terminal = GND
8	V.OUT	V ₈	2.8	3.5	4.3	v	—
9	SDA	٧g	4.8	5.1	5.4	v	—
10	SCL	V ₁₀	4.8	5.1	5.4		—
11	N.C.	V ₁₁	_	0.0	_		Terminal = GND
12	I ² L GND	V ₁₂	_	0.0	_		Terminal = GND
13	V.IN	V ₁₃		0.0			Terminal = GND
14	Т.С.	V ₁₄	3.7	4.0	4.3		_
15	V.RAMP	V ₁₅	3.7	4.0	4.3		_
16	V.AGC	V ₁₆	_	0.0	—		Terminal = GND

(Note) Data : Preset

AC CHARACTERISTICS

No.	ITEM	SYM- BOL	с	BL ON DA	TRO)L	TEST METHOD	MIN.	TYP.	MAX.	UNIT
1	Vertical Trigger Input Threshold Voltage	VTH13	40 06 00 0A	03 10 07	04 00 08 00 0C	08 09	 Change the height of trigger pulse given to TP13, and measure the time pulse height when a timing pulse is output. ^{20ms} ^{640/µs} ¹³ ¹³ ^{TP14} ¹³ ^{TP13} ^{Pin 13} ^{4V} ^V ¹³ ^{TP13} ^{Pin 14} ^(*) All data are preset. 	0.7	1.0	1.4	V
2	Clamp Voltage At TP14	V _{H14}	40 06 00 0A	03 10 07 20 08 00	00 08 00 0C	08 09	 Give the trigger pulse to TP13. (Pulse width : 640µs, cycle : 20ms, Low level : 0V, High level : 3V). Observe the wave shape at TP14. ^{3V} Pin 13 0V ^V Pin 13 ^V VH14 ^V VH14 ^V VL14 	3.7	4.0	4.2	V
3	Threshold Voltage I At TP14	VM14	40 06 00 0A	03 10 07 20 0B 00	00 08 00 0C	08 09 00	 Same as No.2. Observe the wave shape at TP14 and TP15. V_{H14} V_{M14} V_{M14} Pin 14 V_{L14} Pin 15 V. RAMP Charging start point 	2.8	3.0	3.2	V

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No.	ITEM	SYM- BOL	C	BL ON DA	TRO)L		TEST METHOD	MIN.	TYP.	MAX.	UNIT
4	Threshold 4 Voltage II At TP14	V _{L14}	40	07	00 08	08 09	•	Same as No.3.	0.9	1.0	1.1	v
			0A 20	0B 00								
	Vertical Ramp 5 Pulse Amplitude	cal Ramp		03 10 07	00	08	•	Measure the vertical ramp pulse amplitude at TP15.				
5		V _{P15}	0A	20 0B 00	0C	00		VP15 Pin 15 (*) All data are preset.	1.9	2.0	2.1	V _{p-p}
				03 10			•	Give no pulse to TP13. Connect an external power supply to TP6. Measure the voltage of TP8				
6	6 Vertical Amplifier Gain	GV	06 00 0A	20	00			when the voltage of TP8 when the voltage of TP6 is changed from 0V to 6V.	22	26	30	dB
					<u>ов</u> 00				V_{L8} Pin 6 DC			

TOSHIBA

No.	ITEM	SYM- BOL	с	Bl ON DA	TRO	L	TEST METHOD	MIN.	TYP.	MAX.	UNIT
				03 10							
	Vertical		06	07	08	09					
7	Amplifier Max. Output Voltage	V _{H8}	00	20	00	00	 Same as No.6. (*) All data are preset. 	2.9	3.6	4.5	v
			0A	0B	0C						
			20	00	00						
			02	03	04	05					
	8 Vertical Amplifier Min. Output Voltage		40	10	00	08			0	0.3	
		mplifier Min. utput	06	07	08	09					
8			00	20	00	00	• Same as No.6.	0			v
			0A	0B	0C						
			20	00	00	00					
			02	03	04	05					
			40	10	00	08	 Same as No.6. Measure the current between TP8 and GND when the voltage 				
	Vertical		06	07	08	09	of TP6 is 6V.				
9	Amplifier Max	Amplifier Max. Dutput Imax8 00 20 0		00	00	6)	20	40	_	mA	
			0A	0B	0C		8— <u>†</u>				
			20	00	00		(*) All data are preset.				

No.	ITEM	SYM- BOL		BL DN DA	rno	L		TEST METHOD	MIN.	TYP.	MAX.	UNIT
10	Vertical Saw Wave Amplitude	V _{P6}	02 40 06 00 0A 20	10 07 20 0B	00 08 00 0C	08 09	•	Same as No.2. Measure the amplitude of saw wave at TP6. (*) All data are preset.	1.7	1.9	2.2	V _{p-p}
11	Vertical Amplitude Variable Range	VPH	02 7F 5 00 06 00 0A 20	10 07 20 0B	00 08 00 0C	08 09	•	Same as No.10. Measure the amplitude VP6 (00) at TP6 when the data of sub address (02) is turned to (00). Measure the amplitude VP6 (3F) at TP6 when the data of sub address (02) is turned to (00). $V_{PH} = \pm \frac{V_{P6} (3F) - V_{P6} (00)}{V_{P6} (3F) + V_{P6} (00)}$ × 100%	+ 45 – 45			U/A
12	Vertical Linearlity Max. Correction	Ve	40 06 00 0A	1F 10 00 07 20	00 08 00 0C	08 09	•	Turn it to (3F) the data of sub address (08) and adjust the data of sub address (0A) for making the shape of parabolic wave of TP4 symmetrical. Turn it to (00) the data of sub address (08). Measure V ₁ (10) and V ₂ (10) at TP6 when the data of sub address (03) is (10). Similarly measure V ₁ (00), V ₂ (CC), V ₁ (1F) and V ₂ (1F). (00) and (1F) are the data of sub address (08). V _ℓ = ± 100 × V_1 (10) + V ₂ (17) - V ₂ (00) $2 \times (V_1$ (10) + V ₂ (10))			+ 15.0 – 15.0	

No.	ITEM	SYM- BOL	BUS CONTROL DATA)L		TEST METHOD	MIN.	TYP.	MAX.	UNIT
	Max. Of Vertical S Correction	Vs	40	03 10	04 1F 00	08		Same as No.12. Measure the amplitude V_{S6} (00) at TP6 when the data of sub address (04) is (00). Measure the amplitude V_{S6} (1F)				
13			00 0A	20 0B		00		at TP6 when the data of sub address (04) is (00). $v_{S6 (1F)} v_{S6 (00)}$	20	24	28	%
			Adjust	00	00			$V_{S} = \frac{V_{S6}(00) - V_{S6}(1F)}{V_{S6}(00)}$ × 100 (%)				
	Max. Of Vertical ∫ Correction	٧f	02	03	04	05	•	Same as No.13. Measure the amplitude V∫6 (00) at TP6 when the data of sub address (0C) is (00).				
			40	10	00	08	•		3			
			06	07	08	09	•	Measure the amplitude $V_{\int 6}$ (OF) at TP6 when the data of sub				
14			00	20	00	00		address (OC) is (OF). $V_{\int G(OF)}$		_	_	%
			0A	0B	0C							
			Adjust	00	0F 00			$V_{\int} = \frac{V_{\int 6 (0F)} - V_{\int 6 (00)}}{V_{\int 6 (00)}}$ × 100 (%)				
			02	03	04	05						
			40	10	00	08	•	Same as No.12.				
			06	07	08	09	•	Observe the wave shape at TP6.				
15	Vertical NF Center Voltage	vc	00	20	00	00		vc	3.8	4.1	4.4	v
			0A	0B	0C			= ≠ = = 10ms 10ms Pin 6				
			Adjust	00	00			Fillo				

No.	ITEM	SYM- BOL	BUS CONTROL DATA			DL		TEST METHOD		TYP.	MAX.	UNIT
16	Vertical NF DC Variation	V _{DC}	40 06 00	03 10 07 20 0B 00	00 08 00 0C	0F 00 09		Same as No.15. Measure the vertical NF center voltage V _C (00) when the data of sub address (05) is (00). Measure the vertical NF center voltage V _C (0F) when the data of sub address (05) is (00). $V_{DC} = \pm \frac{V_C (0F) - V_C (00)}{2} (V)$	±720	± 800	± 880	mV
17	Vertical Amplitude EHT Correction	V _{EHT}	40 06 0F 00	10 07	00 08 00 0C	08 09 00	•	Same as No.12. Connect an external power supply to TP1 and turn its voltage to 0V. Measure the amplitude V _{EHT} (00) at TP6 when the data of sub address (06) is (00). Measure the amplitude V _{EHT} (0F) at TP6 when the data of sub address (06) is (0F). $V_{EHT} = \frac{V_{EHT} (00) - V_{EHT} (0F)}{V_{EHT} (00)}$ × 100 (%)	8	9	10	v
18	EHT Input Dynamic Range I	V _{H1}	40 06 0F	03 10 07 20 0B 00	00 08 00 0C	08 09 00	•	Same as No.17. Change it from 1V to 7V the voltage of the external power supply connected with TP1. At this time, measure the variation of amplitude at TP6.	6.0	6.5	7.0	v

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No.	ITEM	SYM- BOL	BUS CONTROL DATA					TEST METHOD	MIN.	TYP.	MAX.	UNIT
			02	03		05						
			40	10	00	08					2.3	
			06	07	08	09	1					
19	EHT Input Dynamic Range II	V _{L1}						Same as No.18.	1.3	1.8		v
			0A	0B	0C							
			Adjust	00	00							
			02	03	04	05						
	E-W NF Max. DC (Picture Width)		40	10	00	08		Same as No.12. Measure the voltage at TP4.				
			06	07	08	09						
20			00	00	00	00			6.8	7.4	8.0	v
			0A	0B	0C							
			Adjust	00	00							
			02	03	04	05						
						08						
			06	07	08	09						
	E-W NF											
21	Min. DC (Picture Width)	V _{L4}					•	Measure the voltage at TP4.	1.4	1.5	1.7	V
			0A	0B	0C							
			Adjust	00	00							

No.	ITEM	SYM- BOL	BUS CONTROL DATA)L		TEST METHOD	MIN.	TYP.	MAX.	UNIT
22	E-W NF Max. Parabolic Correction (Parabola)	V _{PB}	40 06 00	03 10 07 3F 0B	04	08 09 00	•	Give 7V to TP1. Measure the parabolic amplitude at TP4. Pin 4	4.8	5.6	6.6	V _{p-p}
23	E-W NF Corner Correction (Corner)	VCR	40 06 00	10 07 3F 0B		08	••••	Give 7V to TP1. Measure the parabolic amplitude at TP4. Measure the amplitude V _{CR} (00) when the data of sub address (09) is (00). Measure the amplitude V _{CR} (0F) when data of sub address (09) is (0F). V _{CR} (0F) V _{CR} (0F) V _{CR} (00) - V _{CR} (0F)	2.5	3.2	4.1	V _{p-p}
24	Parabolic Symmetry Correction	VTR	40 06 00	10 07 20 0B	08 00	08 09 00		Same as No.10. Measure the vertical scan center voltage V _C (00) at TP6 when the data of sub address (0A) is (00). Measure the vertical scan center voltage V _C (3F) at TP6 when the data of sub address (0A) is (3F). V _{TR} = $\pm \frac{V_C (00) - V_C (3F)}{2 \times V_{P6}}$ × 100 (%) V _C $\longrightarrow_{10ms} 10ms$	±3	±4.5	±6	%

No.	ITEM	SYM- BOL	BUS CONTROL DATA)L		TEST METHOD		TYP.	MAX.	UNIT
		V _{EH1}	40		00	05 08 09		Same as No.22. Connect an external power supply to TP1. Measure the parabolic amplitude V _{EH} (7) at TP4 when the voltage of TP1 is 7V. Measure the amplitude V _{EH} (1) when the voltage of TP1 is 1V. $V_{EH1} = \frac{V_{EH} (7) - V_{EH} (1)}{V_{EH} (7)}$ × 100 (%)				
25	E-W Parabolic EHT Correction		00 0A			00	•		_	4.7	_	%
			djust	00		0.5						
	E-W DC EHT Correction	V _{EH2}	40	03 10 07	00	08	•	Give 1V to TP1. Measure the parabolic phase center voltage V _{PC} (00) at TP4 when the data of sub address (0B) is (00). Measure the voltage V _{PC} (0F) when the data is (0F). $V_{PC (0F)} - V_{PC (0F)}$ $V_{EH2} = V_{PC} (0F) - V_{PC} (00)$	1.0	1.4	1.8	V
26				3F	3F							
			Adjust §	00 ‡ 0F	00							
			02	03	04	05						
						10	•	Connect an ampere meter between TP2 and GND.				
	Max. Of E-W		06	07	08	09	•	Measure the current.				mA
27	Amplifier Output Current	I _{max2}	00	20	00	00	-		0.14	0.2	0.27	
			0A	0B	0C							
			20	00	00							

(Note) Concerning fall time

When used in actual applications, if the fall time for input pulse becomes greater output may not be generated in some cases, so please take care.

CHARACTERISTIC	TEST METHOD	MIN.	TYP.	MAX.	UNIT
Trigger Input Fall Time	As below	—	1.0	7.6	μs

While monitoring the input waveform of Pin 13 oscilloscope, please measure fall time from 10% to 90%.

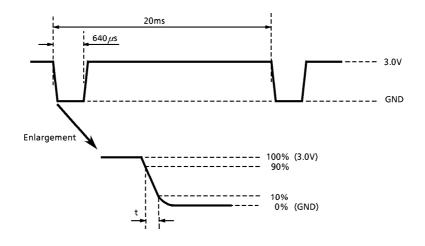
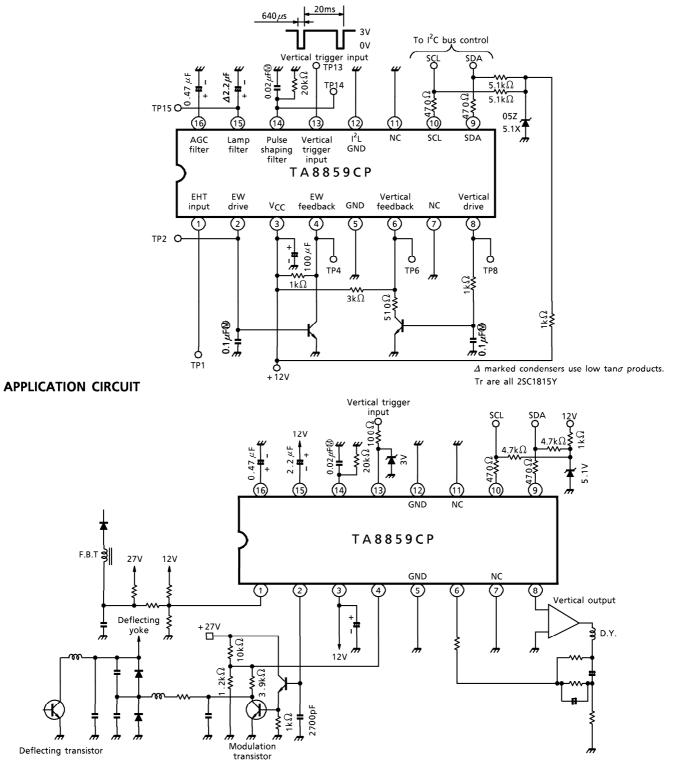


Fig.

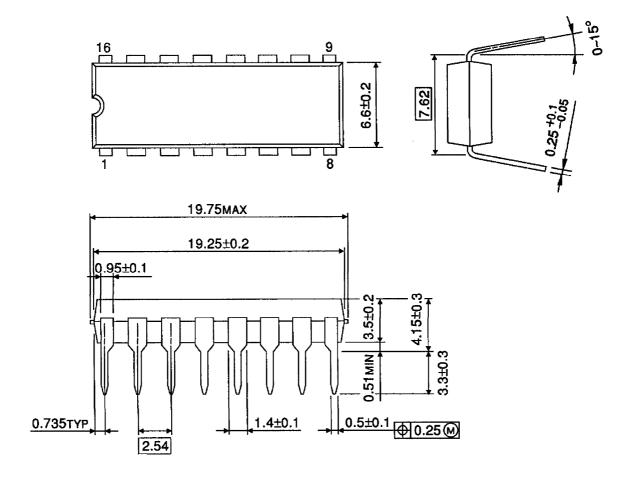
<u>TOSHIBA</u>

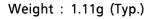
TEST CIRCUIT



PACKAGE DIMENSIONS DIP16-P-300-2.54B

UNIT : mm





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000707EBA

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